

Underactuated Robotic Hands

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abstract— this paper describes a novel underactuated robotic hand design. tpthe hand is highly underactuated as it contains three fingers with three joints ...

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fig. 1. i-hy is an underactuated hand capable of performing a wide range of tasks, including fingertip grasping and manipulation. 2 task analysis and hand design

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d e s c r i p t i o n . underactuated robotic hand . the object of the present invention is a robotic hand of the type specified in the preamble of the first claim.

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